

# 2013년도 제15회 한국 MEMS 학술대회 논문집

## Proceedings of The 15th Korean MEMS Conference

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## 2013년도 제15회 한국 MEMS 학술 대회 일정

날짜	시간	내용	장소
4월 4일 목요일	16:00~18:00	등록	로비(그랜드볼룸앞)
	17:30~19:00	리셉션	로비(그랜드볼룸앞)
4월 5일 금요일	07:30~18:00	등록	로비(그랜드볼룸앞)
	08:00~09:20	구두 발표 FO-1 (Bio/Biomimetic MEMS)	그랜드볼룸 좌장: 김상호, 박재성
	09:20~09:30	휴식	
	09:30~09:50	개회식	그랜드볼룸
	09:50~10:20	초청강연 (Invited talk) 이상훈 (고려대학교)	그랜드볼룸 좌장: 이대식, 최낙원
	10:20~11:30	포스터 발표 FP-1	무궁화룸, 로즈룸, 동백룸 좌장: 임시형, 이정철
	11:30~12:00	특별강연(강관형 교수 추모) 김성재 (서울대학교)	그랜드볼룸 좌장: 서갑양
	12:00~13:20	중식	
	13:20~14:40	구두 발표 FO-2 (Micro Sensors)	그랜드볼룸 좌장: 윤준보, 백창욱
	14:40~15:00	휴식	
	15:00~15:30	초청강연 (Invited talk) 홍병희 (서울대학교)	그랜드볼룸 좌장: 김종백, 박재형
	15:30~16:50	구두발표 FO-3 (Nano/Micro Materials and Fabrication Technology)	그랜드볼룸 좌장: 김준원, 이성호
	16:50~18:00	포스터 발표 FP-2	무궁화룸, 로즈룸, 동백룸 좌장: 정기훈, 지창현
	18:30~20:30	만찬	그랜드볼룸
4월 6일 토요일	07:30~12:00	등록	로비 (그랜드볼룸앞)
	08:00~09:20	구두발표 SO-4 (Optical MEMS, RF MEMS, Power MEMS and Miscellaneous)	그랜드볼룸 좌장: 박재영, 조일주
	09:20~10:30	포스터 SP-3	무궁화룸, 로즈룸, 동백룸 좌장: 박정열, 정석
	10:30~11:50	구두발표 SO-5 (Microfluidics)	그랜드볼룸 좌장: 서태석, 한기호
	11:50~12:00	우수논문 시상 및 폐회	그랜드볼룸

- |         |  |    |
|---------|--|----|
| FO-2-01 | 정전용량형 극미세 피부 입모근 수축 인지센서<br>김재민, 서대건, 조영호*<br>한국과학기술원 바이오및뇌공학과   | 9  |
| FO-2-02 | 물 속에 용해된 가스의 실시간 감지를 위한 수중 마이크로 가스 감지기<br>이재민, 조동진, 김성은, 이민철, 고종수*<br>부산대학교 기계공학부  | 11 |
| FO-2-03 | Silver nanowire network based stretchable strain sensor<br><sup>1</sup> Aekachan Pichitpajongkit, <sup>1</sup> Morteza Amjadi, <sup>1</sup> Daejong Yang, <sup>1</sup> Jaehwan Lee, <sup>1</sup> Hyeonjin Eom,<br><sup>2</sup> Werapon Kamonkhantikul, <sup>1</sup> Inkyu Park*<br><sup>1</sup> Department of Mechanical Engineering, KAIST, <sup>2</sup> Department of Nano-Engineering, Chulalongkorn University, Thailand | 13 |
| FO-2-04 | 표면 온도센서 어레이를 이용한 고온 열유속 측정<br><sup>1</sup> 안철희, <sup>1</sup> 나병준, <sup>1</sup> 김형훈, <sup>2</sup> 도규형 <sup>2</sup> 이정호 <sup>1</sup> 고정상*<br><sup>1</sup> 부산대학교 기계공학부, <sup>2</sup> 한국기계연구원 에너지기계연구본부  | 15 |

Invited Talk 2

4 월 5 일 금요일

15:00 ~ 15:30

좌장: 김종백, 박재형

홍병희

서울대학교 화학부

Graphene-Based MEMS: Challenges and Opportunities

Oral Session 3 (FO-3) ~~Mano~~/Micro Materials and Fabrication Technology

4 월 5 일 금요일

15:30 ~ 16:50

좌장: 김준원, 이성호

- |         |   |    |
|---------|---|----|
| FO-3-01 | SOI 마이크로머시닝 공정을 이용한 현수된 산화아연 나노막대 기반 가스 센서의 제작 및 특성 평가<br>이경훈, 권대성, 김민욱, 나형주, 김종백*<br>연세대학교 기계공학과   | 17 |
| FO-3-02 | 유리기판 관통 고종횡비 구리 비아 어레이의 제작<br>이성우, 이주용, 김준호, 이승기, 박재형*<br>단국대학교 전자전기공학부   | 19 |
| FO-3-03 | Preparation and Characterization of PDMS-based graphene composite for sensor applications<br>Bo Wang, Bong-Ki Lee, <sup>1</sup> Dong-Weon Lee*<br>School of Mechanical Engineering, Chonnam National University | 21 |

# Preparation and Characterization of PDMS-based graphene composite for sensor applications

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## Abstract

The primary objective of this research is to fabricate the graphene nanopowder composite based on polydimethylsiloxane (PDMS) and characterize the sensitivity of the graphene/PDMS composite. The fabrication of graphene/PDMS composite can be accomplished by simple and fast sonication and stir processes. The piezoresistive characteristics of graphene/PDMS composite can play the same role as piezoresistor in strain sensors and with the average gauge factors between 6.25 and 277 which obtained within the strain range of 2%. The graphene/PDMS strain sensor showed much higher strain sensitivity than strain sensors and the strain gauge made of other carbon filler composite, the applicability of the composite are demonstrated in this research.

Keywords: *graphene, composite, strain sensor, piezoresistive*

## 1. Introduction

Sensors based on nanocomposites have been attracting interest recently due to their strain sensing characteristics. For instance, strain sensors based on CNTs composite [1] [2], carbon black/polymer composite[3], or graphene foam[4] serves as good candidates for developing new hybrid materials-based strain sensors due to their outstanding performance. Graphene, the perfect two-dimensional (2D) crystalline carbon sheet with high Young's modulus and high strength, when used as conductive filler in polymers, graphene not only improve the mechanical properties but also present new functionality. Graphene composites have the potential to realize a higher sensitivity to strain and wider applicability comparing to graphene itself [4] due to the unique superiority of composite and easy to be processed.

Our research demonstrates the preparation and characterization of graphene/PDMS composites for use in strain sensor applications. The piezoresistive property of composites reported as sensing material are of gauge factor value no higher than that demonstrated in our research, which showed great potential for use in MEMS application.

## 2. Experimental

### 2.1 Fabrication and measurement of graphene/PDMS composite

The fabrication of graphene/PDMS composite relies on the common evaporation technique[5]. The PDMS (Sylgard 184) was purchased from Dow Corning Co. and the graphene nanopowder (MO-1) from Graphene Supermarket. The appropriate amounts of THF were firstly added into the base polymer to decrease the viscosity of base polymer. The graphene was dispersed into THF with a ratio of 300mg graphene nanopowder per 20ml by using

ultrasonicator (ultrasonic power 200W) for 2 hours. Afterwards the dispersed graphene/THF solution was mixed with the base polymer solution by using ultrasonicator for 4 hours to form PDMS base polymer/graphene composite in THF and decrease the macroscopic graphene clusters in the solution. The THF evaporation was processed in a fume hood by stirring the solution at 50°C. The curing agent was added to the dispersed graphene/PDMS base polymer emulsion. Then, the blended graphene/PDMS mixture emulsion was degassed for 30 min. Finally, the mixed composite was uniformly smeared onto 4mm-thick PDMS specimens. In order to fabricate a sensor, the smeared composite was cut into rectangular shape by blades, and cured at 60°C in oven for 10 h. The final graphene/PDMS composite samples on PDMS specimens have thicknesses between 100 μm and 300 μm. Two electrodes were connected to it with silver conducting epoxy to improve the contact as shown in Fig.1. The perfect bond between PDMS and the composite ensure the transfer of strain across the sensor simultaneous during the measurement.

### 2.2 Measurement

The piezoresistivity of the composite was investigated with source meter (Keithley 2400). The elongation of the specimen was exerted and measured with universal test machine (SHIMADZU EZ-Test 500N), the loading speed was numerically controlled at 0.5mm/min.

## 3. Results and discussions

In order to characterize the sensitivity of the graphene/PDMS composite, the gauge factor (GF) of the composite could be obtained with the equation

$$GF = \frac{\frac{\Delta L}{L}}{\frac{\Delta R}{R}} \quad (1)$$

where  $R$  is the initial resistance of the sensor and  $\Delta R$  is the relative resistance change under the deformation.  $L$  is the initial length of the sensor and  $\Delta L$  is the relative elongation of the axial specimen. The relative resistance change of graphene/PDMS composites with different filler concentrations with respect to the applied strain ( $\epsilon$ ) is shown in Fig.2. The average gauge factors for different concentration of graphene are illustrated in Fig.3 which lies between 6.25 and 277.

The sensitivity can be explained from macro level and micro viewpoint. From a macroscopic point of view, the strain response of graphene/PDMS composites strongly depends on the contact resistance of surrounding graphene flakes. The piezoresistivity may come partly from slippage of graphene flakes in the PDMS matrix which is difficult to measure based on the strain response of the sensor. What is more, the deformation of graphene flakes improves the sensitivity of the composite. Increasing the graphene



contact resistance induces the higher resistivity of the composites. Higher strain sensitivity of graphene composites can be explained that the larger inter-contact area among the graphene due to their special 2-D structure. The linear change can also be explained by the fact that the graphene flake bent and extended due to the loading strain and form contacts with multiple adjacent graphene nanopowder. The hysteresis is existed in the composite since PDMS, the viscoelastic polymer matrix with property of elasticity and viscosity, which is presented by a purely viscous damper and purely elastic spring connected in parallel named as Kelvin-Voigt model. The hysteresis is mostly due to the relaxation time of the polymer matrix which results in the shortage for reciprocating strain monitoring applications. The investigation was not systematically performed and further studies on composite flexibility are still needed.

#### 4. Conclusions

This paper reported the fabrication and electromechanical characterization of graphene nanopowder composite based on PDMS. Graphene/PDMS composite shows a linear piezoresistive response with gauge factor between 6.25 and 277 within the strain range of 2%. The high sensitivity which can be explained by the increase of graphene flake contact areas and the deformation of graphene itself, makes it a material with potential to be used for sensing tensile deformation by changes in strain.

#### Acknowledgment

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#### References

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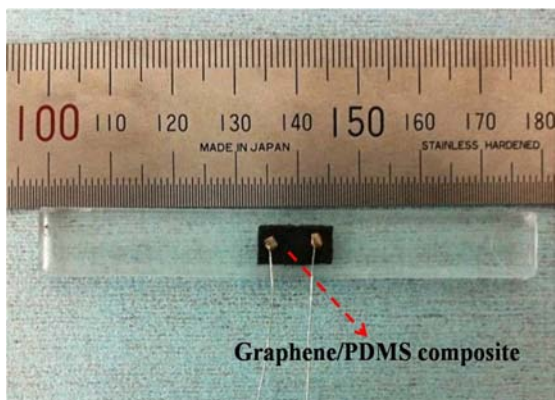


Fig. 1 PDMS Specimen with graphene/PDMS composite for tensile tests

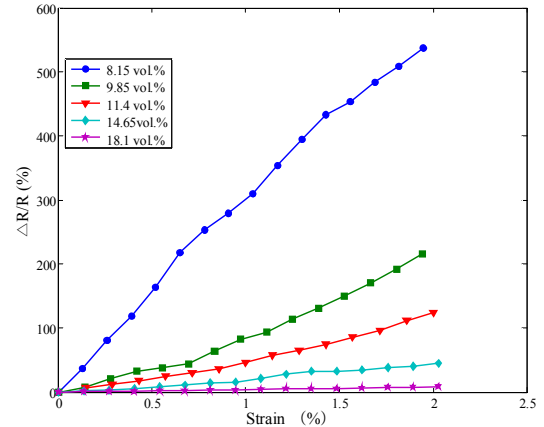


Fig. 2 Composite (with different volume fraction) resistance change with tensile strain

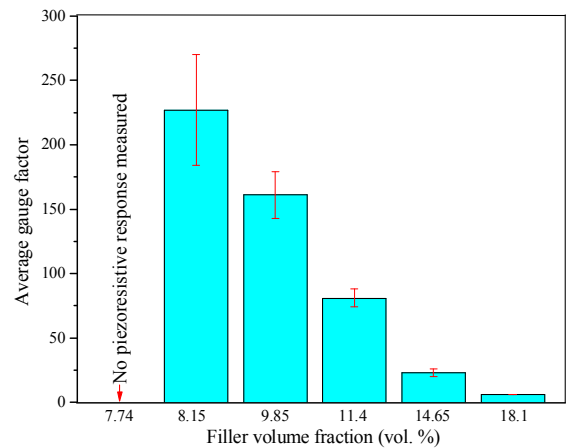


Fig. 3 Average gauge factors of graphene/PDMS composite with different filler volume fraction